Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L2	13	display\$4 same (three-dimenson\$4 3-d 3d) and robot near2 (model\$4 image representation) and animat\$4 and (@ad<"19991012" @rlad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON .	2005/02/02 15:04
L3	10	display\$4 same (three-dimenson\$4 3-d 3d) same animat\$4 and robot near2 (model\$4 image representation) and (@ad<"19991012" @rlad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/02 15:08
L4	1	display\$4 same (three-dimenson\$4 3-d 3d) same animat\$4 and robot near2 (model\$4 representation) and (@ad<"19991012" @rlad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/02 15:08
L5	2	display\$4 same (three-dimenson\$4 3-d 3d) and animat\$4 and robot near2 (model\$4 representation) and (@ad<"19991012" @rlad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/02 15:09
L6	9	display\$4 same animat\$4 and (three-dimenson\$4 3-d 3d) and robot near2 (model\$4 representation) and (@ad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/02 15:13
L7	. 0	display\$4 same animat\$4 and (three-dimenson\$4 3-d 3d) same robot near2 (model\$4 representation) and (@ad<"19991012" @rlad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/02 15:09
L8	5	display\$4 same animat\$4 and (three-dimenson\$4 3-d 3d) same robot same (model\$4 representation) and (@ad<"19991012" @rlad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/02 15:13
L9	57	display\$4 same animat\$4 and (three-dimension\$4 3-d 3d) near2 (model\$4 representation) and robot and (@ad<"19991012" @rlad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/02 15:13
L10	7	display\$4 same animat\$4 and (three-dimension\$4 3-d 3d) near2 (model\$4 representation) same robot and (@ad<"19991012" @rlad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/02 15:16
L11	11	display\$4 same animat\$4 and (three-dimension\$4 3-d 3d) near2 (model\$4 representation image) same robot and (@ad<"19991012" @rlad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/02 15:16

L12	5	display\$4 same animat\$4 same (three-dimension\$4 3-d 3d) same (model\$4 representation image) same robot and (@ad<"19991012" @rlad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/02 15:28
L13	2	display\$4 same animat\$4 same (three-dimension\$4 3-d 3d) same (model\$4 representation image) same robot and (store storage) same (model\$4 representation image) and (@ad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/02 15:59
L15	1	display\$4 same animat\$4 and (store storage) same (three-dimension\$4 3-d 3d) same (model\$4 representation image) same robot and (@ad<"19991012" @rlad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/02 16:00
L16	3	display\$4 same animat\$4 and (store storage database) same (three-dimension\$4 3-d 3d) same (model\$4 representation image) same robot and (@ad<"19991012" @rlad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/02 16:02
L17	13	display\$4 same animat\$4 and (store storage database) and select\$4 and (three-dimension\$4 3-d 3d) same (model\$4 representation image) same robot and (@ad<"19991012" @rlad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR .	ON	2005/02/02 16:14
L18	1	display\$4 same animat\$4 and ((store storage database) and select\$4) same (three-dimension\$4 3-d 3d) same (model\$4 representation image) same robot and (@ad<"19991012" @rlad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/02 16:19
L19	193	display\$4 same animat\$4 and (store storage database) with (model\$4 representation image) and (three-dimension\$4 3-d 3d) same (model\$4 representation image) same (robot part workpiece work adj piece machine equipment) and select\$4 with (model\$4 representation image) and (@ad<"19991012" @rlad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON .	2005/02/02 16:23

L20	96	display\$4 same animat\$4 and (store storage database) with (model\$4 representation image) and (three-dimension\$4 3-d 3d) with (model\$4 representation image) with (robot part workpiece work adj piece machine equipment) and select\$4 with (model\$4 representation image) and (@ad<"19991012" @rlad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/02 16:23
L21	85	display\$4 same animat\$4 and (store storage database) with (model\$4 representation image) and (three-dimension\$4 3-d 3d) with (model\$4 representation image) with (robot part workpiece work adj piece machine equipment) and select\$4 near3 (model\$4 representation image) and (@ad<"19991012" @rlad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/02 16:24
L22	. 62	display\$4 with animat\$4 and (store storage database) with (model\$4 representation image) and (three-dimension\$4 3-d 3d) with (model\$4 representation image) with (robot part workpiece work adj piece machine equipment) and select\$4 near3 (model\$4 representation image) and (@ad<"19991012" @rlad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/02 16:30
L24	29	display\$4 with animat\$4 and (store storage database) with (model\$4 representation image) and (three-dimension\$4 3-d 3d) with (model\$4 representation image) with (robot and part workpiece work adj piece machine equipment) and select\$4 near3 (model\$4 representation image) and (@ad<"19991012" @rlad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/02 16:33
L25		display\$4 with animat\$4 and (store storage database) with (model\$4 representation image) and (three-dimension\$4 3-d 3d) with (model\$4 representation image) with (robot and (part workpiece work adj piece machine equipment)) and select\$4 near3 (model\$4 representation image) and (@ad<"19991012" @rlad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/02 16:33

L26	1	display\$4 with animat\$4 and (store storage database) with (model\$4 representation image) and (three-dimension\$4 3-d 3d) with (model\$4 representation image) with (robot and (part workpiece work adj piece machine equipment)) and select\$4 with (model\$4 representation image) and (@ad<"19991012" @rlad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/02 16:34
L27	1	display\$4 with animat\$4 and (store storage database) with (model\$4 representation image) and (three-dimension\$4 3-d 3d) with (model\$4 representation image) with (robot and (part workpiece work adj piece machine equipment)) and (@ad<"19991012" @rlad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/02 16:35
L28	1	display\$4 with animat\$4 and (store storage database) and (three-dimension\$4 3-d 3d) with (model\$4 representation image) with (robot and (part workpiece work adj piece machine equipment)) and (@ad<"19991012" @rlad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/02 16:35
L29	1	display\$4 same animat\$4 and (store storage database) and (three-dimension\$4 3-d 3d) with (model\$4 representation image) with (robot and (part workpiece work adj piece machine equipment)) and (@ad<"19991012" @rlad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/02 16:36
L30	38	display\$4 and animat\$4 and (store storage database) and (three-dimension\$4 3-d 3d) with (model\$4 representation image) with (robot and (part workpiece work adj piece machine equipment)) and (@ad<"19991012" @rlad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/02 16:35
L31	38	display\$4 and animat\$4 and (store storage database) and (three-dimension\$4 3-d 3d) with (model\$4 representation image) with (robot\$2 and (part workpiece work adj piece machine equipment)) and (@ad<"19991012" @rlad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/02 16:38

L32	1	display\$4 same animat\$4 and (store storage database) and (three-dimension\$4 3-d 3d) with (model\$4 representation image) with (robot\$2 and (part workpiece work adj piece machine equipment)) and (@ad<"19991012" @rlad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/02 16:36
L33	2	display\$4 same animat\$4 and (three-dimension\$4 3-d 3d) with (model\$4 representation image) with (robot\$2 and (part workpiece work adj piece machine equipment)) and (@ad<"19991012" @rlad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/02 16:36
L34	4	display\$4 and animat\$4 and (store storage database) with (model\$4 representation image robot\$2 part workpiece work adj piece machine equipment) and (three-dimension\$4 3-d 3d) with (model\$4 representation image) with (robot\$2 and (part workpiece work adj piece machine equipment)) and (@ad<"19991012" @rlad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/02 16:41
L35		display\$4 same animat\$4 and (store storage database) same (model\$4 representation image robot\$2 part workpiece work adj piece machine equipment) and (three-dimension\$4 3-d 3d) with (model\$4 representation image) with (robot\$2 and (part workpiece work adj piece machine equipment)) and (@ad<"19991012" @rlad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/02 16:44
L36	0	display\$4 same animat\$4 and (store storage database) same (model\$4 representation image robot\$2 part workpiece work adj piece machine equipment) and (three-dimension\$4 3-d 3d) with (model\$4 representation image) near2 (robot\$2 and (part workpiece work adj piece machine equipment)) and (@ad<"19991012" @rlad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/02 16:44

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L37	0	display\$4 same animat\$4 and (store storage database) same (model\$4 representation image robot\$2 part workpiece work adj piece machine equipment) and (three-dimension\$4 3-d 3d) same (model\$4 representation image) near2 (robot\$2 and (part workpiece work adj piece machine equipment)) and (@ad<"19991012" @rlad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/02 16:58
L38	0	display\$4 same animat\$4 and (store storage database) and (three-dimension\$4 3-d 3d) same (model\$4 representation image) near2 (robot\$2 and (part workpiece work adj piece machine equipment)) and (@ad<"19991012" @rlad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/02 16:58
L39	0	display\$4 same animat\$4 and (three-dimension\$4 3-d 3d) same (model\$4 representation image) near2 (robot\$2 and (part workpiece work adj piece machine equipment)) and (@ad<"19991012" @rlad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/02 16:58
L40		display\$4 and animat\$4 and (three-dimension\$4 3-d 3d) same (model\$4 representation image) near2 (robot\$2 and (part workpiece work adj piece machine equipment)) and (@ad<"19991012" @rlad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/02 16:58
L41	40	display\$4 and animat\$4 and (three-dimension\$4 3-d 3d) and (model\$4 representation image) near2 (robot\$2 and (part workpiece work adj piece machine equipment)) and (@ad<"19991012" @rlad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/02 16:59
L42	33	display\$4 same animat\$4 and (three-dimension\$4 3-d 3d) and (model\$4 representation image) near2 (robot\$2 and (part workpiece work adj piece machine equipment)) and (@ad<"19991012" @rlad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/02 16:59
L43	33	display\$4 same animat\$4 and (store storage database data adj base) and (three-dimension\$4 3-d 3d) and (model\$4 representation image) near2 (robot\$2 and (part workpiece work adj piece machine equipment)) and (@ad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/02 17:00

L44	33	display\$4 same animat\$4 and (store storage database data adj base) and select\$4 and (three-dimension\$4 3-d 3d) and (model\$4 representation image) near2 (robot\$2 and (part workpiece work adj piece machine equipment)) and (@ad<"19991012" @rlad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/02 17:00
L45	17	display\$4 same animat\$4 and ((store storage database data adj base) and select\$4) with (model\$4 representation image) and (three-dimension\$4 3-d 3d) and (model\$4 representation image) near2 (robot\$2 and (part workpiece work adj piece machine equipment)) and (@ad<"19991012" @rlad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/02 17:16
L46	16	display\$4 with animat\$4 and ((store storage database data adj base) and select\$4) with (model\$4 representation image) and (three-dimension\$4 3-d 3d) and (model\$4 representation image) near2 (robot\$2 and (part workpiece work adj piece machine equipment)) and (@ad<"19991012" @rlad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/02 17:17
L47	0	display\$4 with animat\$4 and ((store storage database data adj base) and select\$4) with (model\$4 representation image) and (three-dimension\$4 3-d 3d) same (model\$4 representation image) near2 (robot\$2 and (part workpiece work adj piece machine equipment)) and (@ad<"19991012" @rlad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/02 17:18
L48	0	display\$4 with animat\$4 and (three-dimension\$4 3-d 3d) same (model\$4 representation image) near2 (robot\$2 and (part workpiece work adj piece machine equipment)) and (@ad<"19991012" @rlad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/02 17:18
L49	0	display\$4 same animat\$4 and (three-dimension\$4 3-d 3d) same (model\$4 representation image) near2 (robot\$2 and (part workpiece work adj piece machine equipment)) and (@ad<"19991012" @rlad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/02 17:19

L50	0	animat\$4 and (three-dimension\$4 3-d 3d) same (model\$4 representation image) near2 (robot\$2 and (part workpiece work adj piece machine equipment)) and (@ad<"19991012" @rlad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/02 17:19
L51	12	(three-dimension\$4 3-d 3d) same (model\$4 representation image) near2 (robot\$2 and (part workpiece work adj piece machine equipment)) and (@ad<"19991012" @rlad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/02 17:23
L52	7	(motion movement animat\$4) and (three-dimension\$4 3-d 3d) same (model\$4 representation image) near2 (robot\$2 and (part workpiece work adj piece machine equipment)) and (@ad<"19991012" @rlad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR .	ON	2005/02/02 17:24
L53	. 6	display\$4 and (motion movement animat\$4) and (three-dimension\$4 3-d 3d) same (model\$4 representation image) near2 (robot\$2 and (part workpiece work adj piece machine equipment)) and (@ad<"19991012" @rlad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/02 17:24
L54	6	(stor\$2 storage data adj base database) and display\$4 and (motion movement animat\$4) and (three-dimension\$4 3-d 3d) same (model\$4 representation image) near2 (robot\$2 and (part workpiece work adj piece machine equipment)) and (@ad<"19991012" @rlad<"19991012")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/02 17:25